



SECOORA

Product Discussion

Thursday October 10, 1:15 - 2:00 PM

Session overview

- Status & limitations of WebCOOS products
- What is working well (& what is not quite there yet)
- Set the stage for siting discussions in science showcase to follow
 - Shoreline change: Joe Long, UNCW
 - Rip currents: Alex Pang, UCSC, & Greg Dusek, NOAA
 - Flooding/CO-OPS stations: Dwayne Porter & Jeremy Cothran, USC, & Greg Dusek, NOAA
 - Situational awareness & object detection: Jeremy Cothran, USC
 - Code implementation: Josh Rhoades, Axiom
- Format: 5 minute presentations from each group
 - Discussion & Q&A on each application

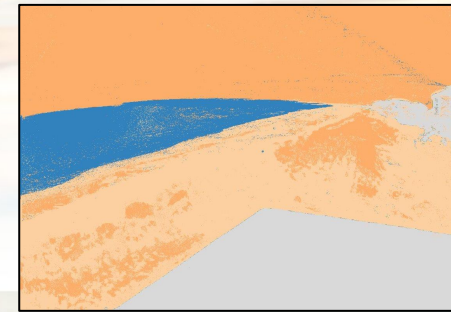
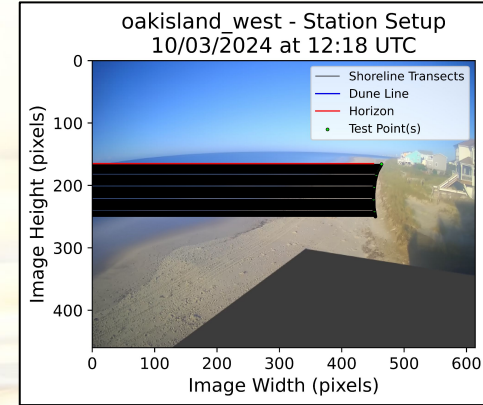
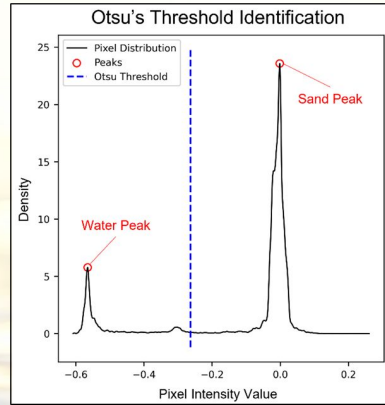


Overall product implementation status

Camera	Shoreline/ wave	Rip currents	Object detection	Flooding	General viewing	Inlet waves
Oak Island east	Y	N	N	N	Y	N
Oak Island west	Y	N	N	N	Y	N
Currituck Hampton inn	Y	Y	M	N	Y	N
Currituck Sailfish	Y	Y	M	N	Y	N
Sheraton Waikiki	M	N	N	N	Y	N
Beaufort Duke Marine lab	N	N	N	Y	Y	N
Charleston Harbor	N	N	Y	Y	Y	N
Holland MI	M	Y	N	N	Y	N
Jennette's North	N	Y	N	N	Y	N
Jennette's South	N	Y	N	N	Y	N
North inlet Winyah bay	N	N	Y	N	Y	N
Point Reyes TMMC	M	N	N	N	Y	N
SC Maritime museum	N	N	N	N	Y	N
UNCW dock North	N	N	M	N	Y	N
UNCW dock south	N	N	M	N	Y	N
Walton Light	M	Y	M	N	Y	N
Cocoa beach	Y	M	N	N	Y	N
Horace Caldwell TX	Y					
Masonboro	N	N	Y	N	Y	Y
Folly 6th	Y	N	Y	N	Y	N
Rosemont Peace 1	N	N	N	Y	N	N
Rosemont Peace 2	N	N	N	Y	N	N
Rosemont Peonie	N	N	N	Y	N	N
LAMC	N	N	N	Y	N	N

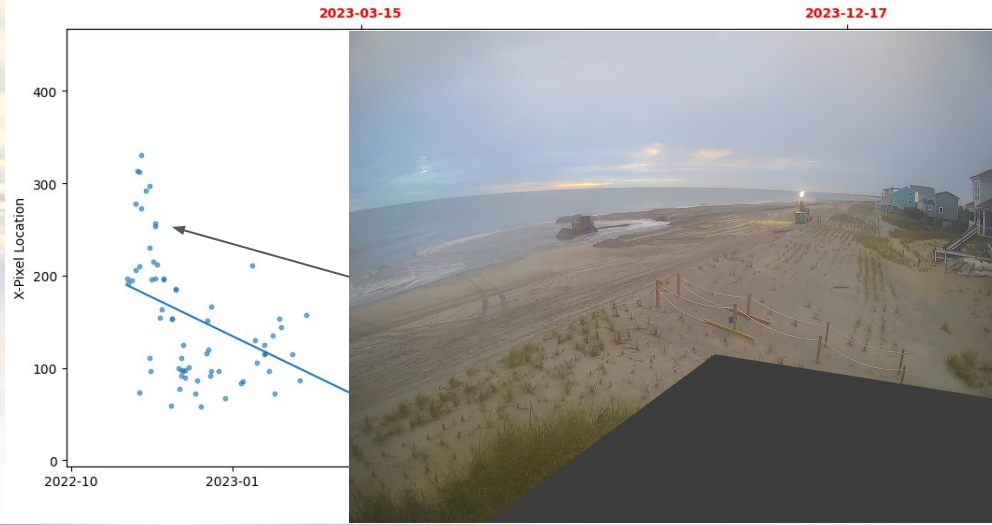
Shoreline change: Joe Long

- Otsu's threshold to identify boundary between water and sand on cross-shore transects
- Each camera relies on a station configuration file
- ML methods tested separately (UNCW & UCSC)



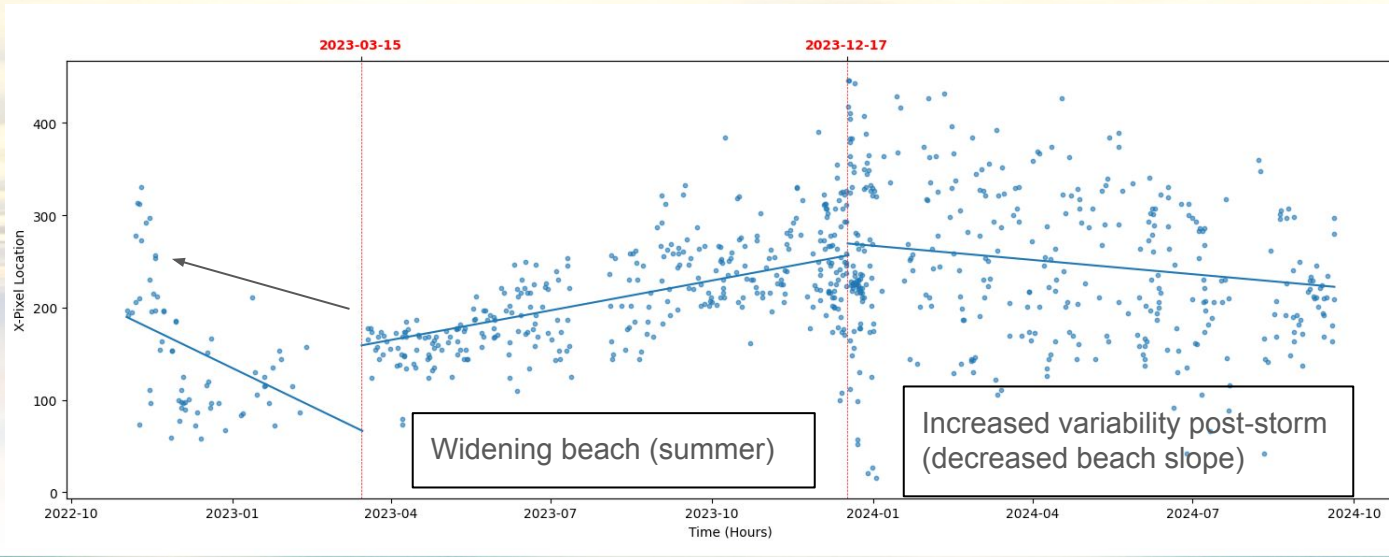
Shoreline change: Trends

- Identify nourishments, seasonal changes, and persistent trends.



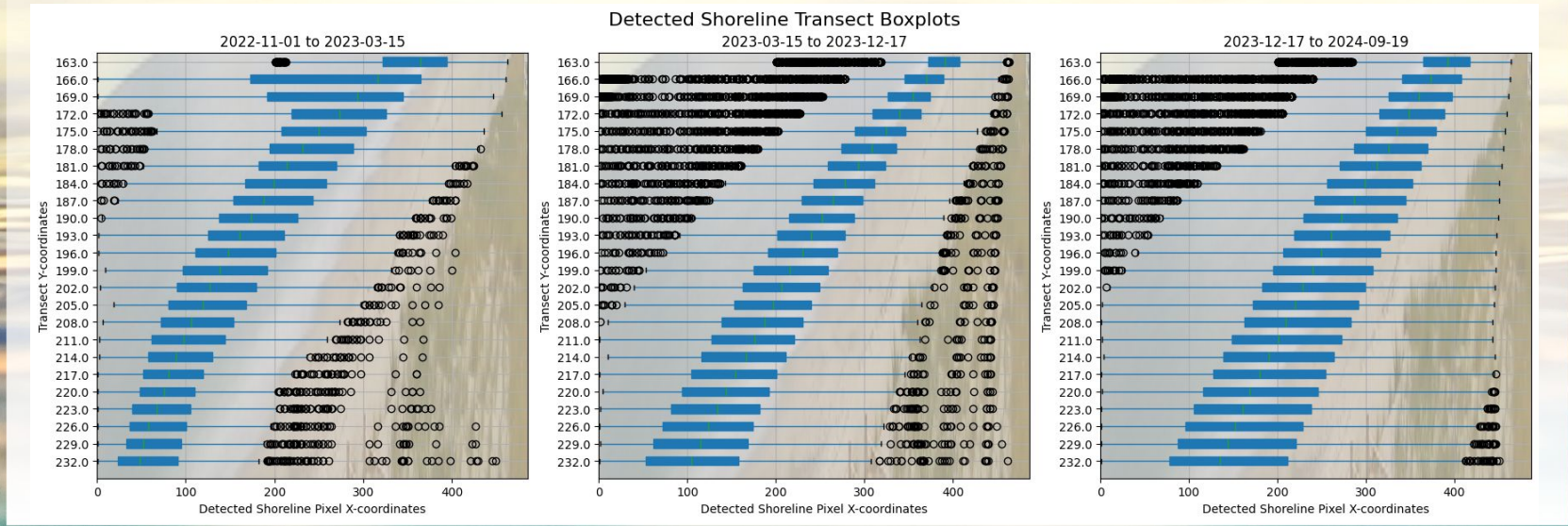
Shoreline change: Trends

- Identify nourishments, seasonal changes, and persistent trends



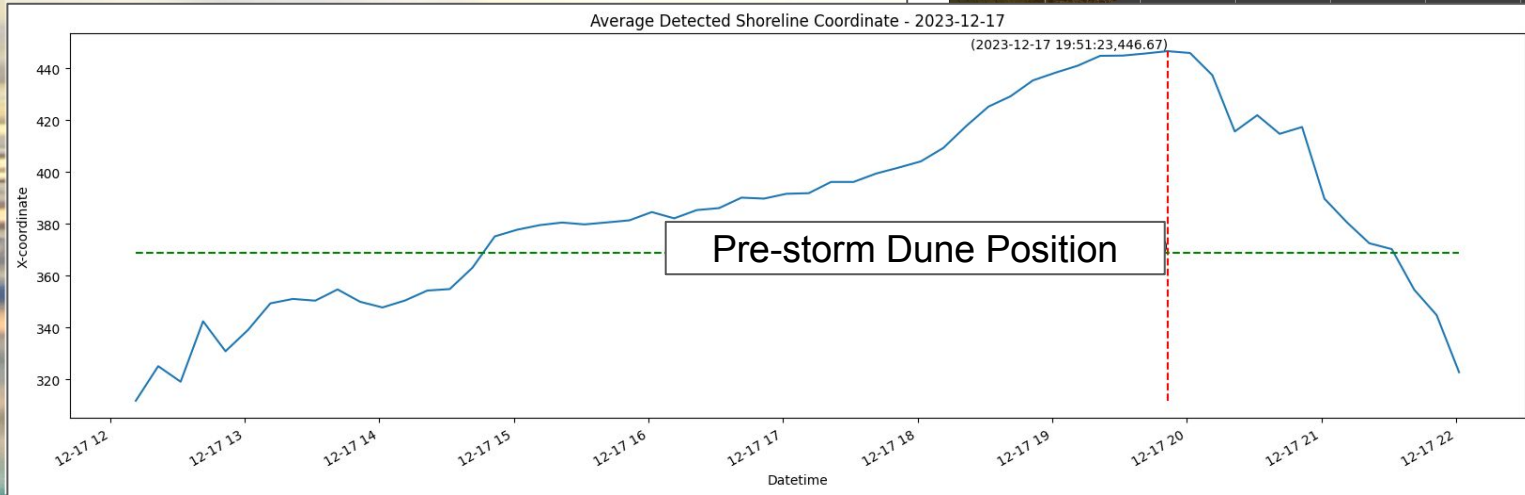
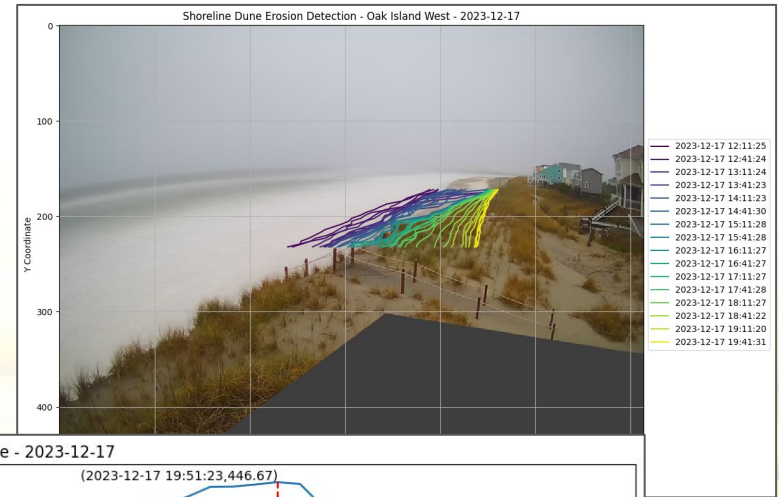
Shoreline change: Trends

- Identify nourishments, seasonal changes, persistent trends.



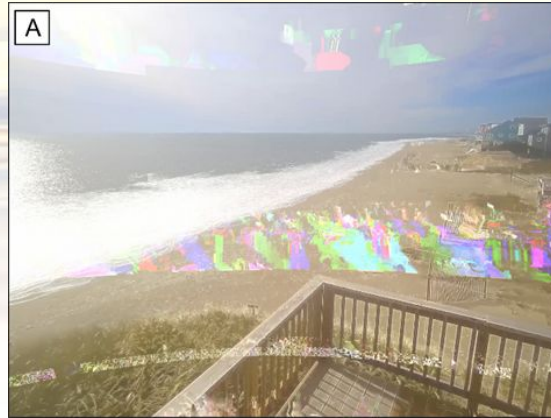
Shoreline change: Storms

- Visualize timing, duration, magnitude of dune erosion events

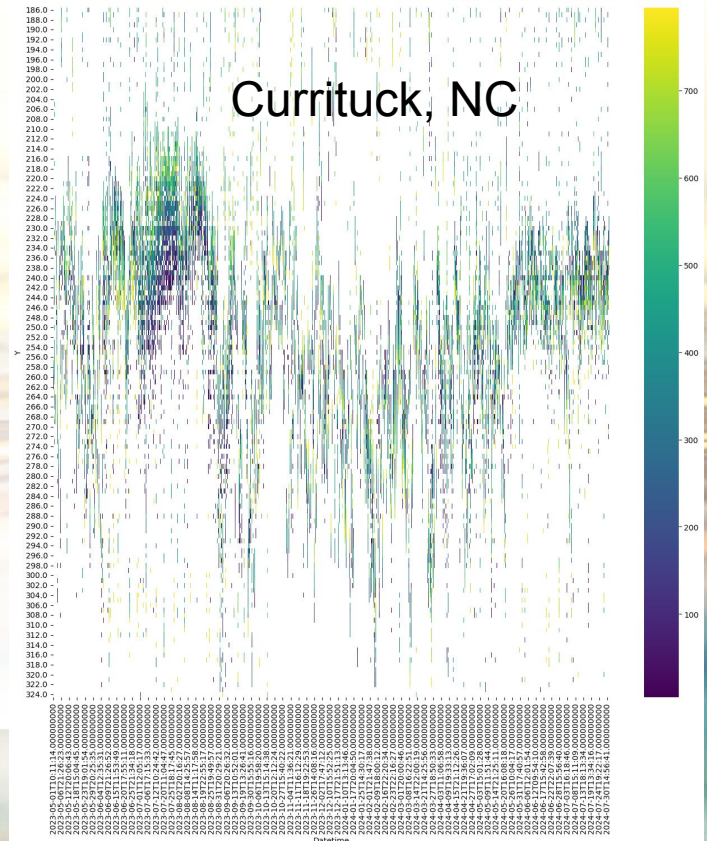
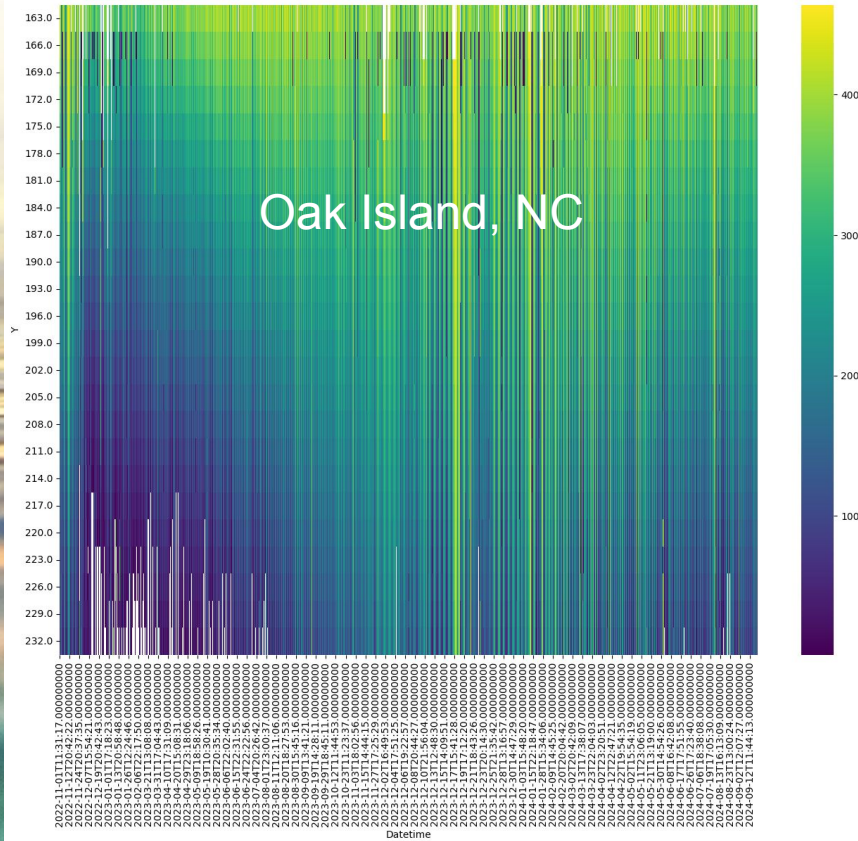


Shoreline change: Limitations

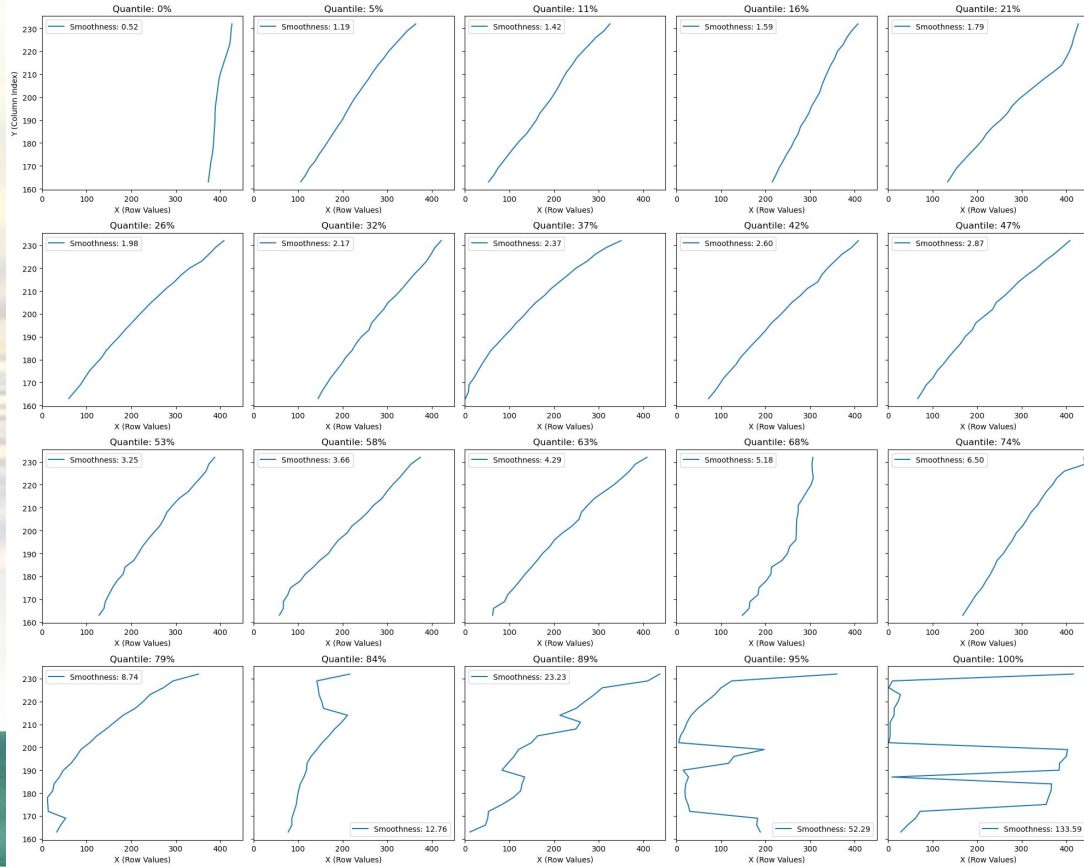
- Pixel-based measurements - not transferable to quantitative change assessments without georectification
- Artifacts of image corruption in time exposure/brightest images
- Rain, fog, camera movement -- the usual suspects!



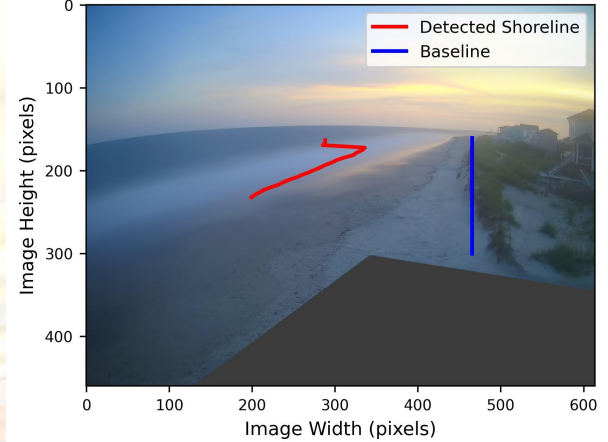
Shoreline change: Not all locations are equal



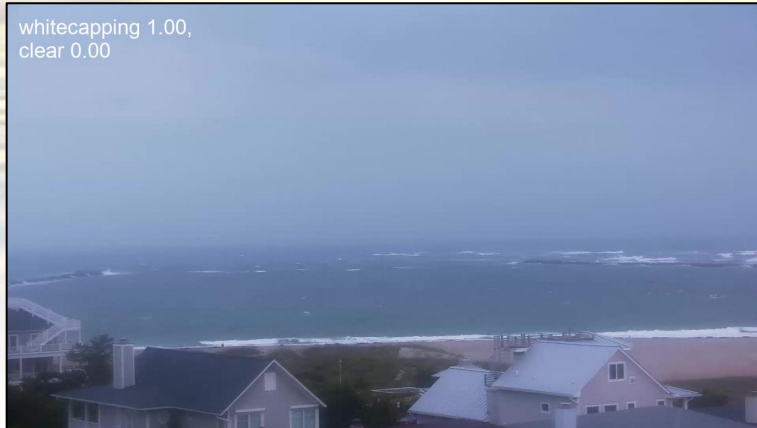
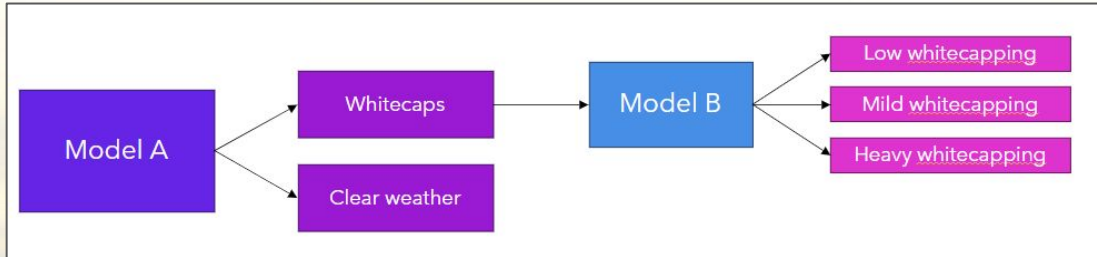
Shoreline change: Good vs. Bad



Transect Based Shoreline Detection (Time Averaged)
Oakisland_west on 2024-07-06 at 02:0 UTC



Inlet Conditions



Rip currents: Alex Pang & Greg Dusek

- Developed 3 classes of methods for rip detection:
Flow Based Approach



Appearance Based Approach



Behavior Based Approach



Rip Detection Status:

- Flow-based requires stable video (not panning, zooming, shaking) and not fully automated
- Behavior-based also requires stable video and GPU (more compute intensive) for near real time performance. Available but not currently deployed.
- Appearance-based can detect rips on a per-frame basis. Currently deployed.



Appearance Based Rip Detection

- Does pretty well when visual signature of rip is strong.
- False negatives when visual signature is weak.
- Requires training data set for each type of rip:
 - Currently bathymetry controlled rips and flash/sediment rips
 - Mostly clear weather. Will need augmentation for environmental factors e.g. fog, cloud/shadows, glare, rain, ...
- Currently deployed at: Walton Lighthouse/CA, Currituck County/NC, Holland Beach/MI
- Site specific customization possible/necessary



Flooding

Rosemont, North Charleston
Peace Street camera



Urban flood extent segmentation and evaluation from real-world surveillance camera images using deep convolutional neural network (Yidi Wang,...)

<https://www.sciencedirect.com/science/article/pii/S1364815223003250?via%3Dihub>

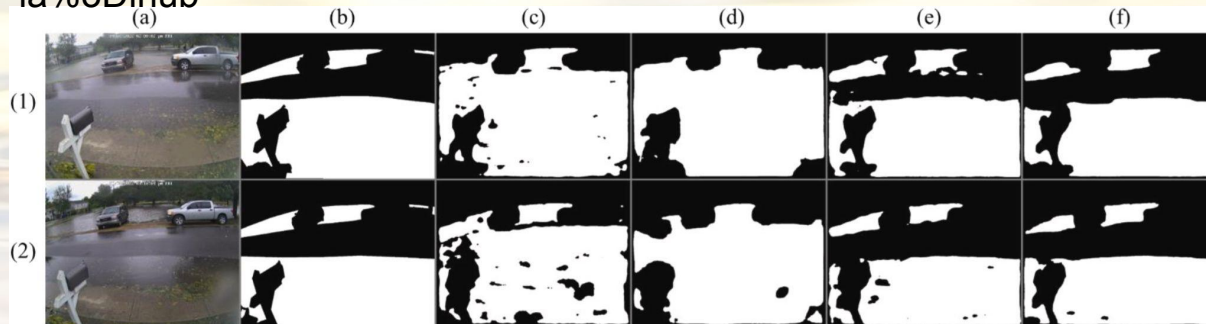


Fig. 5. Examples of model performance in validation. From top to bottom, the four cases are: (1) slightly wavy water surface with normal illumination, (2) still water surface with specular reflection, (3) wet road surface, and (4) night condition. In each case, the six images from left to right are: (a) the original image, (b) ground-truth flood extent, (c) segmented flood extent using Deeplabv3+, (d) image masked with Deeplabv3+ result, (e) segmented flood extent using LinkNet, and (f) image masked with LinkNet result.

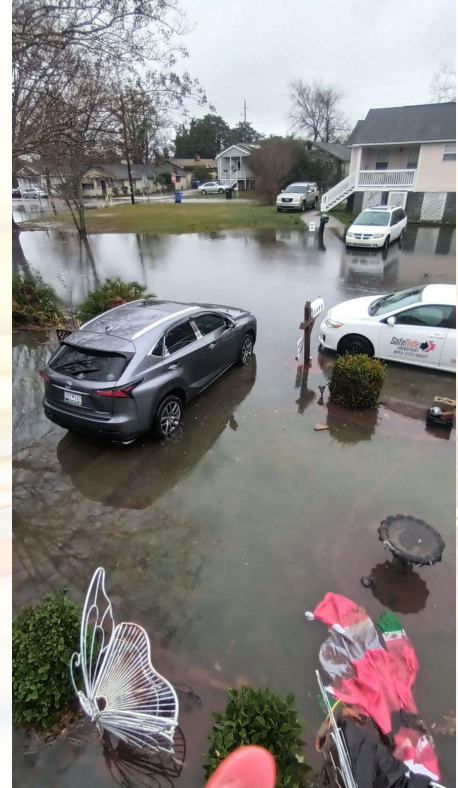


Whaley Way

No flooding, October 2, 2024



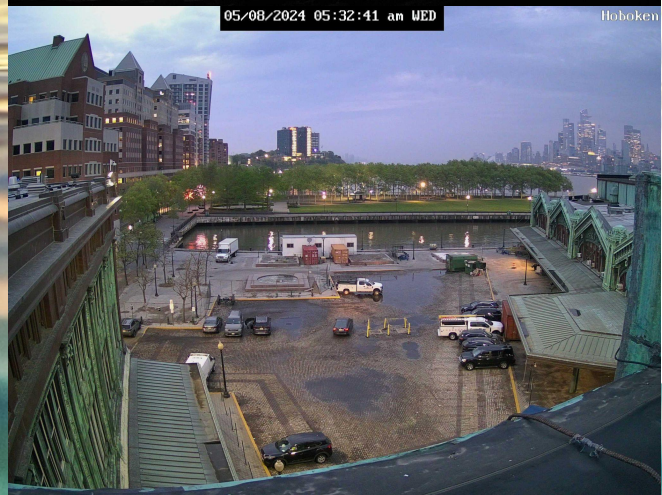
flooding, December 17, 2023



Hoboken, NJ - Stevens Institute of Technology (Philip Orton, Shima Kasaei)
Flooding May 7, 2024, nighttime background lighting sufficient with this camera

Roboflow <https://universe.roboflow.com>

- Publicly available image datasets and models
- Online sample testing and APIs
- Free and paid tier pricing



How to Use the water Detection API

Use this pre-trained water computer vision model to retrieve predictions with our hosted API or deploy to the edge. [Learn More About Roboflow Inference](#)

Switch Model:

v1 water-uzqur/1

Trained On: water-uzqur 21425 Images View Version →

Model Type: Roboflow 2.0 Semantic Segmentation

mIoU

77.1%

View Model Graphs →

Samples from Test Set



Upload Image

Drop file here or

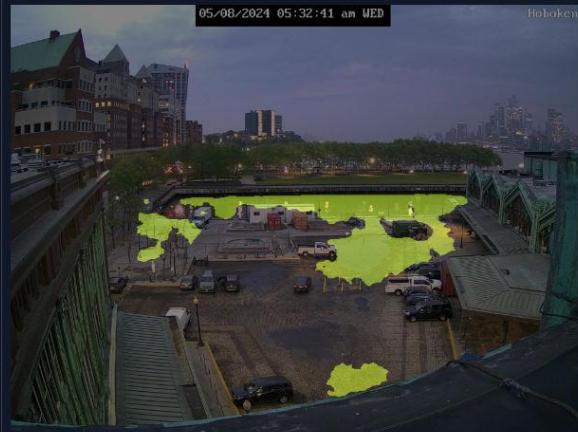
Select File

Paste YouTube or Image URL



Paste a link...

</> Try On My Machine



Opacity Threshold: 44%

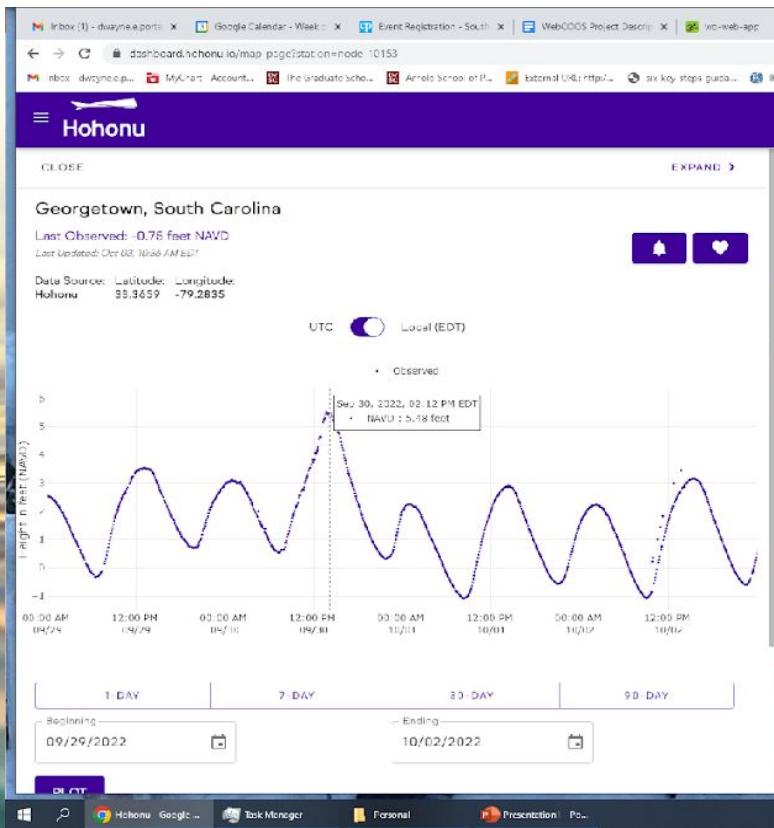
0% 100%

```
{
  "predictions": {
    "segmentation_mask": "iv80",
    "class_map": {
      "0": "background",
      "1": "water"
    },
    "image": {
      "width": 2048,
      "height": 1536
    }
  }
}
```

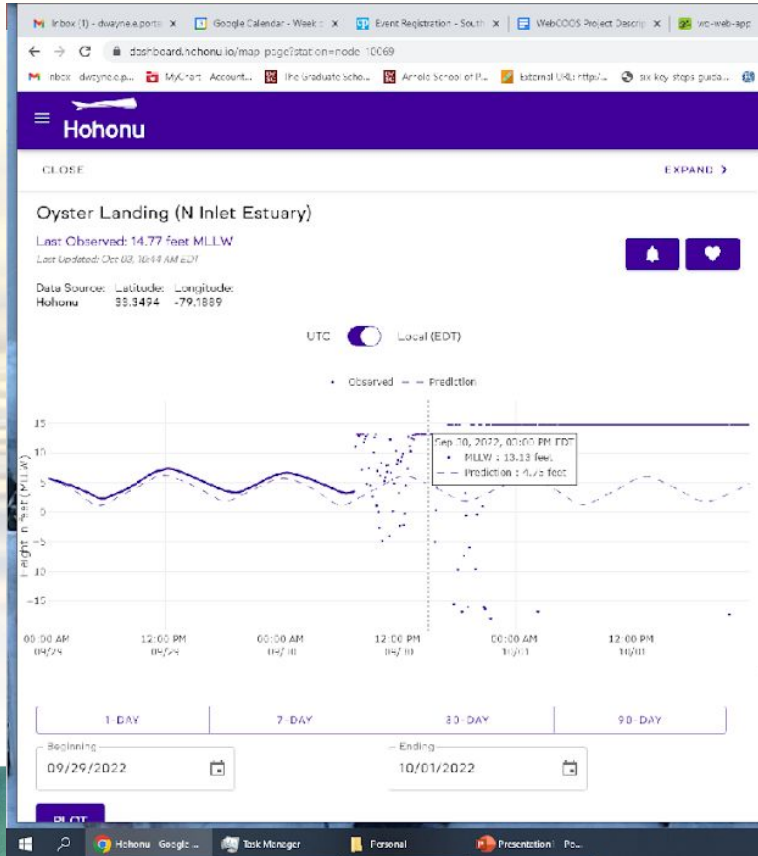
Copy



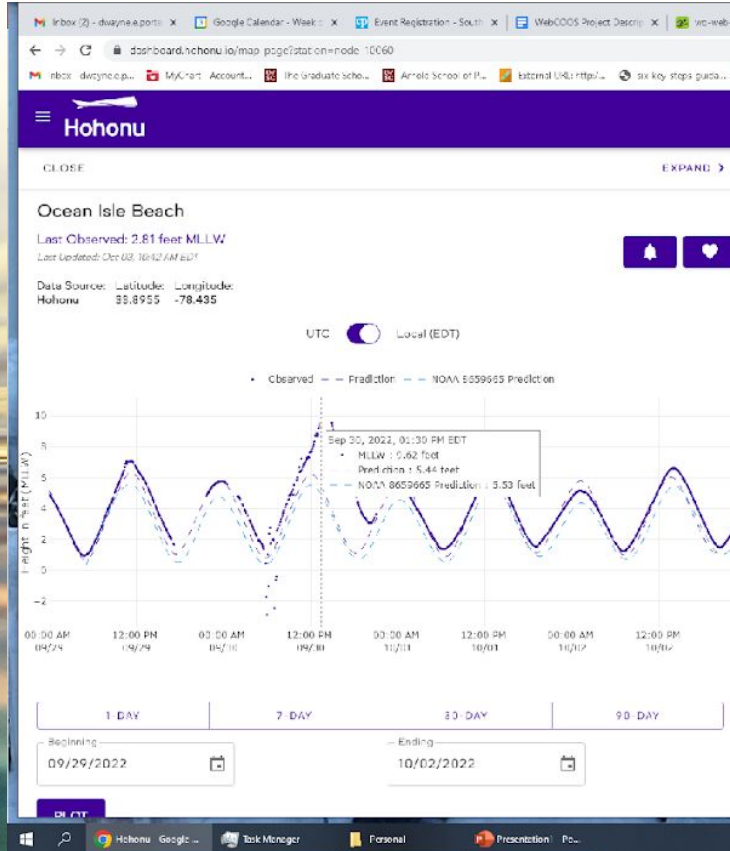
South Carolina Maritime Museum WebCOOS Camera and Water Level Sensor - Hurricane Ian



North Inlet-Winyah Bay NERR – Hurricane Ian



Ocean Isle Beach, NC - Hurricane Ian



Situational awareness/object detection

- YOLO (You Only Look Once)
- <https://docs.ultralytics.com/models/yolov8/>
- 'COCO' dataset (person, vehicle, etc)
- Lowered confidence threshold to 10%
- 10-30% missed or false detections, trends of more use than accuracy



Worked with object detection, though classification and segmentation may be more appropriate depending on the use case



Situational awareness & reporting

Object Detection (person,...)



Alert/notification thresholds

saludaysys.org/notifypage/alert_user_webcoos.php?action=get&session=R08bWU62B

Alerts

Type	Location	Activate	Delete
person_count_gt_20	noaa_currutuck_hampton_inn	Activate	Delete
person_count_gt_20	noaa_currutuck_sailfish	Activate	Delete
person_count_gt_30	noaa_currutuck_sailfish	Mute	Delete
person_count_gt_5	noaa_currutuck_sailfish	Activate	Delete

Add Alert

Please choose alert type and location and click the 'Add' button to add the alert. Maximum of 8 alerts total. In the alert listing above, the 'Mute' button will deactivate the alert and can be toggled back on with the replaced 'Activate' button. The 'Delete' button will delete the alert.

Type: Location: Add

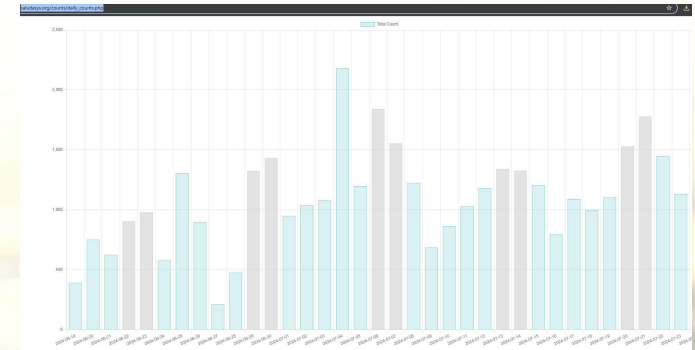
Alert Types

- Person count > 5, the detected count of people is greater than 5, alert resets after 16 hours
- Person count > 20, the detected count of people is greater than 15, alert resets after 3 hours
- Person count > 30, the detected count of people is greater than 20, alert resets after 1 hours

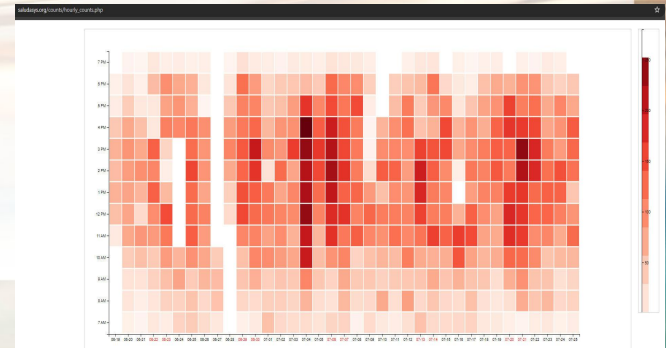
Locations

To review WebCOOS camera locations further:
[Currutuck_Sailfish_Activity_Graph](#)
[Currutuck_Sailfish_Camera](#)
[Currutuck_Hampton_Inn_Activity_Graph](#)
[Currutuck_Hampton_Inn_Camera](#)




Daily status or activity summary








Hourly activity summary



Text/Email notification

auto-alert: person count > 30 (at 34) at noaa_currutuck_sailfish   

 midnightreary7@gmail.com Sat, Aug 10, 2:51 PM    

person count > 30 (at 34)
 location noaa_currutuck_sailfish
 count https://saludaysys.org/counts/detect_webcoos.php?filenname=curretuck_sailfish-2024-08-10-1845432_lpg&obj_type=person&station=noaa_currutuck_sailfish&action=get
 activity https://saludaysys.org/counts/index_webcoos.php?cam=noaa_currutuck_sailfish
 camera: https://webcoos.org/cameras/curretuck_sailfish/

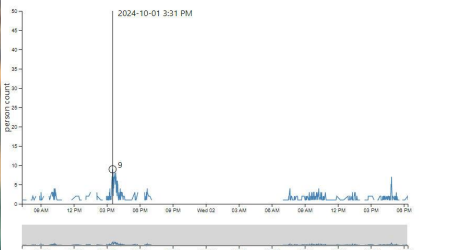
Notification settings: <https://saludaysys.org/notifypage/login.php?type=webcoos>

Activity graph (time vs counts, links to images)

saludaysys.org/counts/index_webcoos.php?cam=noaa_currutuck_sailfish

Camera: currutuck_hampton_inn | Object type: person | Choose other date range: 30 day window | Draw Graph | Graph link

Date Range: 2024-10-1 to 2024-10-4 | Timezone local to camera



To zoom in/out the graph area, click-hold and drag the gray box edges. To move the window, click-hold and drag the gray box.

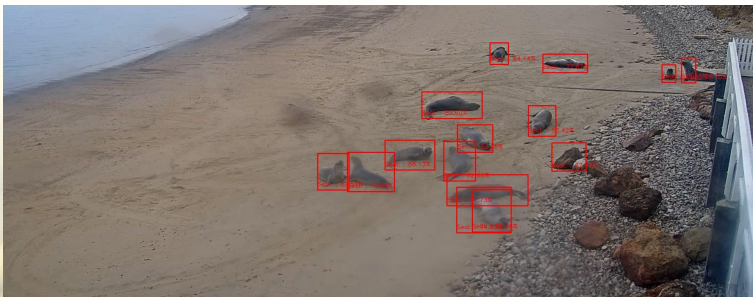
The links below are the associated datetime and count for the selected date range. The link will show the image and detections associated with the count in a new browser tab. The image may be slow to load and if the image fails to load, try reloading the tab.

- [2024-10-01 3:30 PM 7](#)
- [2024-10-01 3:31 PM 9](#)
- [2024-10-01 3:33 PM 4](#)
- [2024-10-01 3:34 PM 2](#)
- [2024-10-01 3:35 PM 4](#)



Problem issues

Good detection(seals)



Missed detections with distance(less pixels/info)



Missed detections due to lack of contrast(lighting) or change in distance or view angle



False detections - shadow contrasts or artifacts?



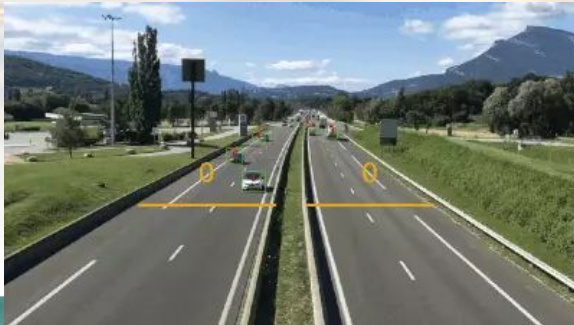
Problem issues

Tried car detection/counting at Isle of Palms beach parking area (lot capacity), but poor results due to

- Low camera angle view
- Occluding vegetation
- Quickly curving road (object rotation)
- Changing lane conditions (available camera view) depending on activity



Optimal traffic view angle - from above to lessen occlusion with minimal object visual rotation/variance



<https://github.com/nathanrooy/rpi-urban-mobility-tracker>
<https://nathanrooy.github.io/posts/2019-02-06/raspberry-pi-deep-learning-traffic-tracker>

Tried Amazon rekognition (persons at beach) - object detection on Amazon Web Services cloud, but default results not as favorable as custom approach and 'custom labels' (on Amazon) more expensive
<https://aws.amazon.com/rekognition>



Additional approaches

- SAHI(Slicing Aided Hyper Inference) slices an image into a set of smaller overlapping images to help detect small objects in larger images
- Mosaic approach - break image into a zones/mosaic(near,far,...) applying different SAHI image size,confidence threshold,...
- Add/Update to imageset used for training
 - Add object classes to differentiate with visually similar objects (e.g. seal vs rock)
- Try other datasets/weight files

Image segmentation(rip tides,flooding,...)

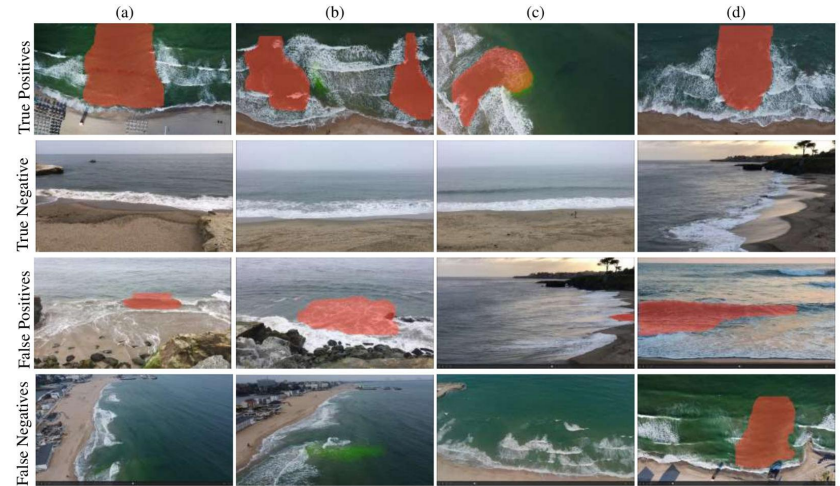


Figure 4. Example of results on testing dataset (using the nano model). On the first two rows we have the correct predictions, the true positives and the true negatives. On the last row we have the incorrect predictions, the false positives and the false negatives. Notice column (d) on the last row, where the model manages to correctly predict one rip current, but misses the second one.



Technology pipeline - could mix and match from different providers

Instrumentation

- Camera resolution
- Perspective / distance
- Programmability/OS/'edge'?
- **Power / connectivity**
- Installation /maintenance

Storage

- Cloud(Amazon S3 object/file buckets)
- Recent / Archived

Video/image collection

Images can be pulled at timed intervals from video via FFmpeg

online/near real-time
push - RTMP/FTP,...
pull - RTSP/HTTP,...

offline
SD card/manual for
deployable/trailcam

Processing(AI/ML,...)

- Cloud / Local, GPU / CPU
Software
- Model (YOLO(You Only Look Once) v8
<https://www.ultralytics.com/yolo>)
- Training set / Weights File (COCO -
Common Objects in Context
cocodataset.org)
- <https://universe.roboflow.com>
- Develop model processing workflow
once and reference 'weight' files for
matching object/class types



Summary

Database(Postgres) - store/query
location,timestamp,object(s)
count,image bbox pixel x/y coords,
confidence score (summary detection
json output)



Products(may reference any previous layers)

- Graphs/Displays
- Summary(Hour,Day,Month) / Reports
- Alerts/Notification



Train/try other datasets/weight files

<https://docs.ultralytics.com/modes/train/>

Roboflow <https://universe.roboflow.com>

- Publicly available image datasets and models
- Online sample testing and APIs
- Free and paid tier pricing

Cloud - develop, train, deploy AI/ML applications

<https://www.paperspace.com>

ChatGPT, Claude, Gemini, ...

Inform, aid and suggest development in discussion and code

How to Use the Beach people Detection API

Use this pre-trained Beach people computer vision model to retrieve predictions with our hosted API or deploy to the edge. [Learn More About Roboflow Inference](#)

Switch Model:
beach-people/3

Trained On: beach-people 887 Images View Version →
Model Type: yolov8s Model Upload


mAP 76.4% Precision 75.2% Recall 78.5%
View Model Graphs →

Samples from Test Set
View Test Set →

Upload Image or Video File
Drop file here or
Select File

Paste YouTube or Image URL
Paste a link...

Try With Webcam
Try On My Machine



```
{ "predictions": [ { "x": 413, "y": 264, "width": 52, "height": 122, "confidence": 0.874, "class": "person", "class_id": 0, "detection_id": "7bfc465"}, { "x": 125, "y": 230, "width": 54, "height": 112, "confidence": 0.864, "class": "person", "class_id": 0, "detection_id": "7bfc465"} ] }
```

11 objects detected

Roboflow Inference

Inference is Roboflow's open source deployment package for developer-friendly vision inference.

How to Deploy the Beach people Detection API

Using Roboflow, you can deploy your object detection model to a range of environments, including:

- Luxonis OAK
- Raspberry Pi
- NVIDIA Jetson
- A Docker container
- A web page
- iOS
- A Python script using the Roboflow SDK.

Below, we have instructions on how to use our deployment options.

Code Snippets

Python cURL Javascript Swift .NET

Hosted API
Infer on Local and Hosted Images

On Device
To install dependencies, 'pip install inference-sdk'.



Code Implementation (challenges and details)

- Challenges with Rip Current Detection
 - Rip current detection requires NVIDIA GPU acceleration (40+ CPU cores cannot serve as a replacement)
 - Have to support multiple rip current models at once
 - Multi-stage products
 - input video → 15-second time average → ML model (general) → detection output
 - input video → once-a-minute still → ML model (walton) → detection output
 - Models, as developed, work with real-time video streams, but Axiom's pipeline isn't wired for that
- Challenges with Shoreline
 - **[Filtered]** Multi-stage products:
 - [Input video, longer than 9 minutes, selected from the top of the hour] → ~10 minute time average → shoreline detection algorithm → shoreline detection product
 - GPU provides negligible improvement, and high CPU during time average and brightest pixel calculations.
 - Heavy config lift for each new camera.
- Challenges with General Object Detection
 - Works well, but have to tweak detection in subtle ways:
 - Filtering out erroneous object detections (can't have trains on beaches, etc.)
 - Had to use a "windowing" feature to better identify objects in frame.
 - PTZ schedules can make for widely different object detection results (as opposed to a fixed camera view)

